



**TS-5624-R02 Series Digital Dual Axis Inclinometer** 

# **Technical Manual**

V1.0



TS-5624-R02

### **FEATURES**

Dual Axis Inclination Measurement

Resolution: 0.001°Power Supply: 9-36V

• Size:  $2.165 \times 1.46 \times 0.94$  (inch)  $55 \times 37 \times 24$  (mm)

Highest Accuracy: 0.02°Measurement Range: ±90°

• Output: RS232/RS485/TTL for optional

IP67 Protection Level

## **APPLICATIONS**

Industrial Automatic Leveling

Medical Instruments

Photovoltaic Automatic Tracking

Tower Tilt Monitoring

Structural deformation monitoring

Surveying and Mapping Instruments

Equipment automation

Lifting Equipment Inclination Control

## **DESCRIPTION**

The TS-5624-R02, developed and manufactured by AIT Sensing, is a cost - effective dual - axis inclinometer. It incorporates a well - established industrial - grade MEMS accelerometer, with a measurement range of  $\pm 90^{\circ}$  and a maximum accuracy of 0.02°. The operating temperature range extends from  $-40^{\circ}$ C to  $+ 85^{\circ}$ C.

Compact and lightweight, the TS-5624-R02 is well suited for applications with space constraints. It converts variations in the static gravity field into changes in the inclination angle.

This inclinometer has numerous advantages, such as low cost, minimal temperature drift, ease of use, and strong anti - interference capabilities. Thus, it is an ideal choice for inclination measurement in industries like photovoltaic power generation, pan - tilt control, and tower monitoring.

During installation, users can employ the AIT serial port debugging assistant tool or AIT test and calibration software for on - site calibration. This helps correct any angle misalignment at the installation site.

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## **SPECIFICATIONS**

Table 1.

| Parameter                   | Test Conditions  | Min. | Тур. | Max. | Unit/Note |
|-----------------------------|------------------|------|------|------|-----------|
| Power Supply Voltage        |                  | 9    | 12   | 36   | V         |
| Operating Current           | No load          | 20   | 30   | 40   | mA        |
| Storage Temperature Range   |                  | -55  | 25   | 100  | °C        |
| Operating Temperature Range |                  | -40  | 25   | 85   | °C        |
| Measurement Range           |                  |      | ±90  |      | 0         |
| Measurement Axis            |                  | Х    | X-Y  |      |           |
| Accuracy                    | Room temperature |      | 0.02 |      | 0         |



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| Parameter                       | Test Conditions    | Min.                       | Тур.  | Max.  | Unit/Note |
|---------------------------------|--------------------|----------------------------|-------|-------|-----------|
| Resolution                      | Completely still   |                            | 0.001 |       | 0         |
| Zero Bias                       | −40°C ~ 85°C       | -0.005                     |       | 0.005 | °/°C      |
| Start-Up Time                   |                    |                            |       | 3     | S         |
| Output Frequency                | 5-100Hz adjustable |                            |       | 100   | Hz        |
| Mean Time Between Failures MTBF |                    | 90000                      |       |       | h         |
| Electromagnetic Compatibility   |                    | According to GBT17626      |       |       |           |
| Insulation Resistance           |                    | 100                        |       |       | ΜΩ        |
| Impact Resistance               |                    | 2000g, 0.5ms, 3 times/axis |       |       |           |
|                                 |                    |                            | 300   |       | g         |
| Weight                          |                    |                            | 0.66  |       | lbs       |
|                                 |                    |                            | 10.6  |       | Oz        |

<sup>\*</sup>Resolution: The smallest change value of the measured value that the sensor can detect and distinguish within the measurement range.

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<sup>\*</sup>Accuracy: The root mean square error of the actual angle and the sensor measuring angle for multiple (≥16 times) measurements.

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## **ELECTRICAL INTERFACE**

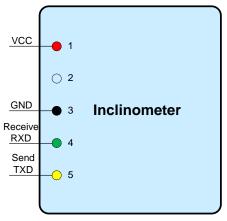


Figure 1. Pin Names

## **Table 2. Pin Number, Colors and Functions**

| No. | Co | olor   | Functions           |  |
|-----|----|--------|---------------------|--|
| 1   |    | Red    | VCC: DC 9V ~ 36V    |  |
| 2   |    | Blue   | -                   |  |
| 3   |    | Black  | Ground              |  |
| 4   |    | Green  | Receive RXD (B 、D-) |  |
| 5   |    | Yellow | Send TXD(A、D+)      |  |

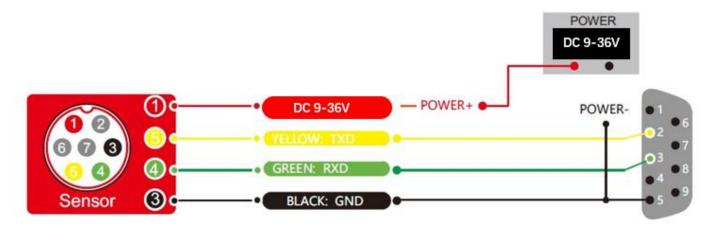


Figure 2. RS 232 Wiring Diagram

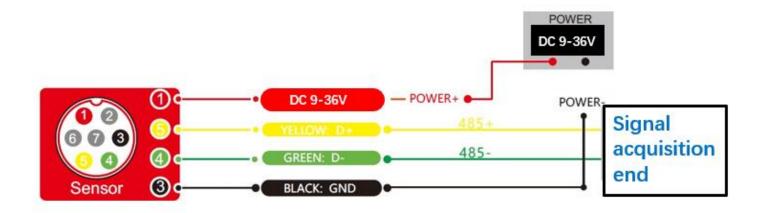


Figure 3. RS 485 Wiring Diagram

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## **DEBUGGING SOFTWARE**

You can download the serial debugging assistant directly on the official website (technical service -> download area), or you can use the more convenient and intuitive host computer software.

TS-5624-R02 supporting serial port debugging software can connect the inclination sensor on the computer to display the angle. The software debugging interface is shown in the figure below. Using the tilt angle to debug the host computer, you can conveniently display the current X direction and Y direction tilt angle, and you can also modify and set other parameters.

#### Steps:

- (1). Correctly connect the serial port hardware of the inclinometer and connect the power supply.
- (2). Select the computer serial port and baud rate and click to connect to the serial port.
- (3). Click Start, the current tilt angle of the inclinometer in the X and Y directions will be displayed on the screen.

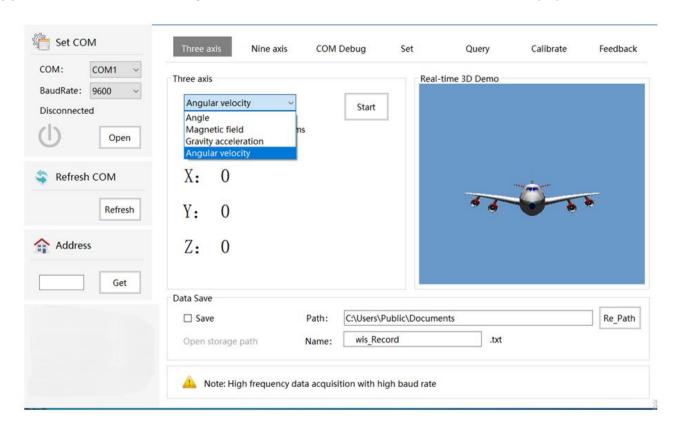


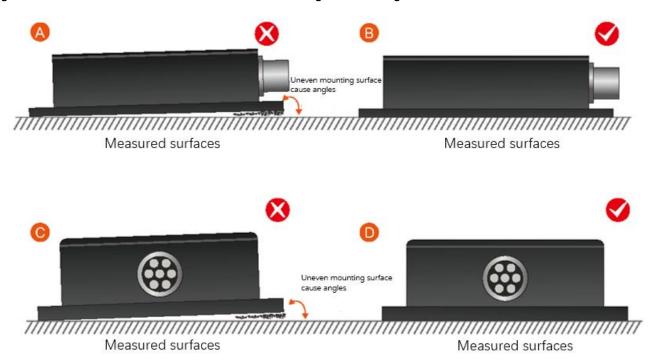
Figure 4. Software Debugging Interface

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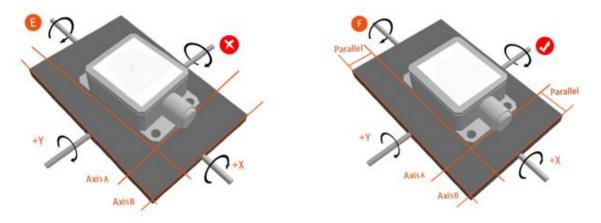
## **INSTALLATION**

The correct installation method can avoid measurement errors. When installing the sensor, please do the following:

First of all, make sure that the sensor mounting surface is completely close to the measured surface, and the measured surface should be as level as possible. There should be no included angles as shown in Figure A and Figure C. The correct installation method is shown in Figure B and Figure D.



Secondly, the bottom line of the sensor and the axis of the measured object cannot have an angle as shown in Figure E, and the bottom line of the sensor should be kept parallel or orthogonal to the axis of rotation of the measured object during installation. This product can be installed horizontally or vertically (vertical installation needs to be customized), and the correct installation method is shown in Figure F.



Finally, the mounting surface of the sensor and the surface to be measured must be tightly fixed, smooth in contact, and stable in rotation, and measurement errors due to acceleration and vibration must be avoided.

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## **DIMENSIONS**

#### **Outline Dimensions**

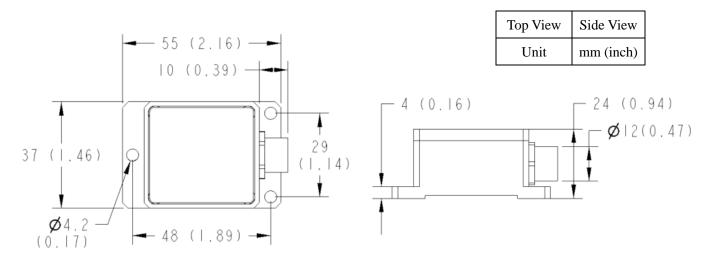


Figure 5. Outline Dimensions

#### **PCB Dimensions**

The length and width may have an error of  $\pm 1$ mm, please refer to the actual product.

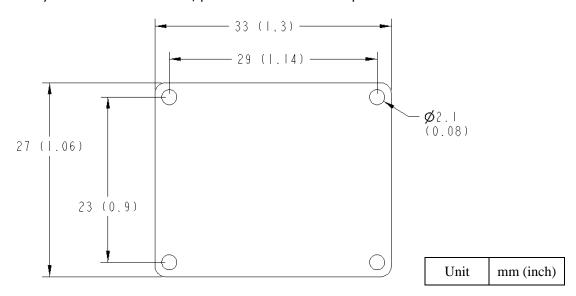


Figure 6. PCB Dimensions

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Figure 7. Top View of TS-5624-R02

Table 3. Mechanical Index

| Connector        | Metal joint (Cable 1.5m)           |
|------------------|------------------------------------|
| Protection level | IP67                               |
| Shell material   | Magnesium aluminum alloy oxidation |
| Installation     | Three M4 screws                    |