



## **IMU-2663-R07 Series High-Precision Inertial Measurement**

# **Technical Manual**

**V1.0**

### FEATURES

- Quadrature Compensation
- Gyro Range:  $\pm 500^\circ/\text{s}$
- Accelerometer Range:  $\pm 20\text{g}$ , Optional  $\pm 5\text{g}$ ,  $\pm 50\text{g}$
- RS422 Interface Output
- Wide Temperature Range:  $-40^\circ\text{C} \sim +85^\circ\text{C}$
- Temperature Compensation
- Small Size:  $1.76 \times 1.52 \times 0.85$  (inch)  
 $44.8 \times 38.6 \times 21.5$  (mm)

### APPLICATIONS

- Pipeline Survey Engineering
- Model Attitude Angle Measurement
- Stable Platform
- Autonomous Driving
- Navigation Platform

### SPECIFICATIONS

Table 1.

Parameter	Min.	Typ.	Max.	Unit/Note
Power Supply Voltage		5		V DC
Operating Current		200		mA
Operating Temperature Range	-40		85	°C
Gyro	Resolution	0.00006		°/s
	Range	$\pm 500$		°/s
	Zero Bias Stability at normal Temperature (10s Smoothing)		5	°/h
	Zero bias repeatability at room temperature		3	°/h
	ARW	0.25		°/ $\sqrt{\text{h}}$
	Zero bias at full temperature (without temperature compensation)	30		°/h
	Zero bias at full temperature (with temperature compensation)		10	°/h
	Scale factor non-linearity		150	ppm
	Bandwidth	200		Hz

- Under Water Robot Navigation
- Unmanned Aerial Vehicle

### DESCRIPTION

IMU-2663-R07 uses highly reliable MEMS accelerometers and gyroscopes with algorithms to ensure the measurement accuracy. Meanwhile, the hermetically sealed design and strict production process ensure that the product can still accurately measure the carrier's angular velocity, acceleration, and other motion parameters under harsh environments. Through the non-linear compensation, quadrature compensation, temperature compensation and drift compensation and other compensation, can greatly eliminate the source of error of IMU-2663-R07, improve the level of accuracy of the product. IMU-2663-R07 has a digital interface, it can be very easy to integrate into the user's system.

Parameter	Min.	Typ.	Max.	Unit/Note
Maximum Output		500		Hz
Start Delay		200		ms

Table 2.

	Parameter	Default Setting	Precision Setting	High Range Setting	Unit/Note
Accelerometer	Range	±20	±5	±50	g
	Resolution	25	12.5	100	µg
	Zero bias stability at room temperature (10s smoothing)	15	8	50	µg
	Normal Temperature Zero Bias Stability (ALLAN)	5	2	10	µg
	Normal temperature zero bias repeatability	10	5	20	µg
	Bandwidth	150	150	150	Hz
	Scale Factor Non-linearity	1500	1500	3000	ppm
	Noise	25	12.5	100	µg/√Hz

## CONNECTIONS

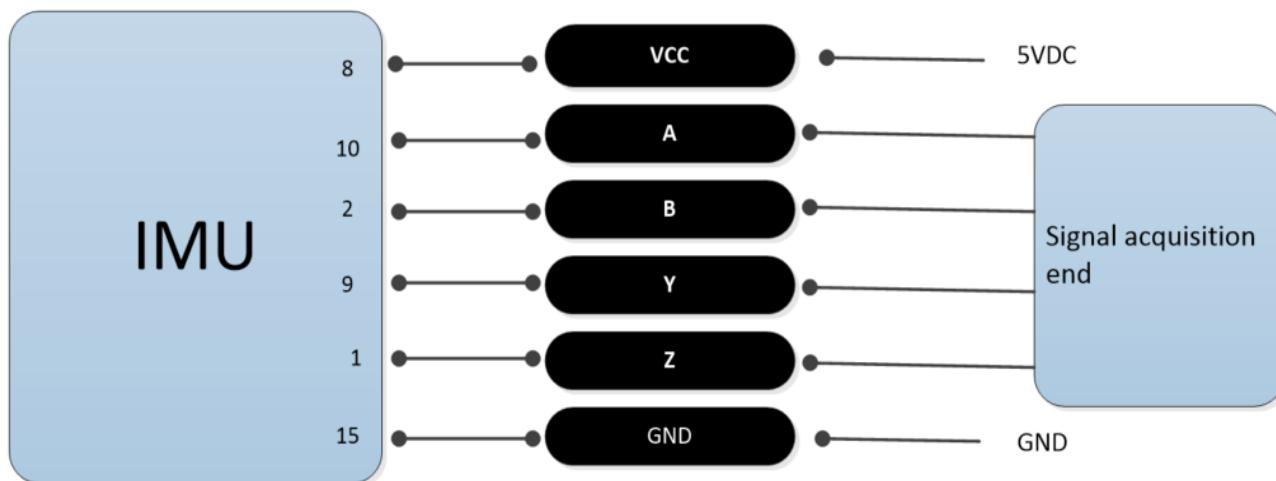


Figure 1. RS422 Wiring Diagram

**Table 3. Pin Number, Colors and Functions**

No.	Color	Functions
8	VCC	DC 5V
15	GND	
2	RXD	(B)
10	RXD+	(A)
1	T/R-	(Z)
9	T/R-	(Y)

### Axial definition

Data axis conforms to the right-hand rule.

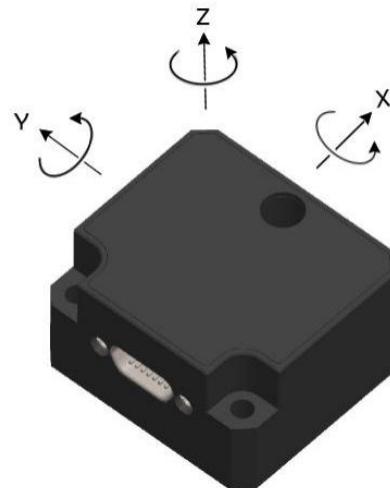


Figure 2. Three-axis attitude, gyroscope & acceleration

## INSTALLATION

The correct installation method can avoid measurement errors. When installing the sensor, please do the following:

First of all, make sure that the sensor mounting surface is completely close to the measured surface, and the measured surface should be as level as possible. There should be no included angles as shown in Figure A and Figure C. The correct installation method is shown in Figure B and Figure D.

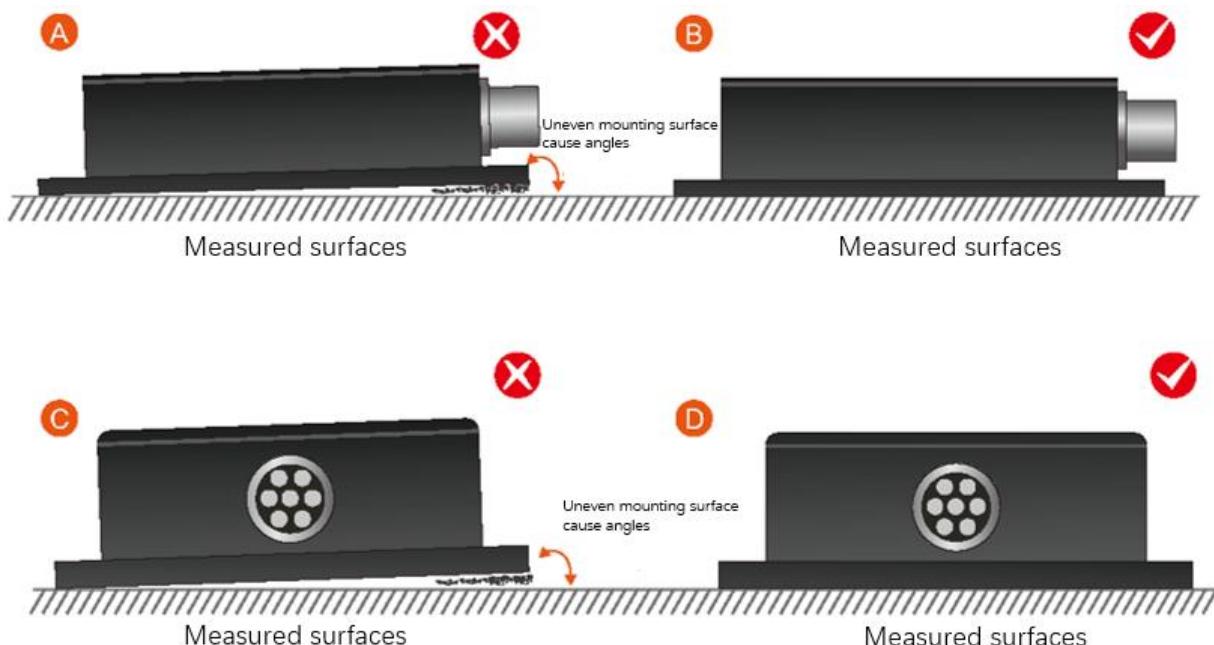


Figure 3. Installation Diagram

Secondly, the bottom line of the sensor and the axis of the measured object cannot have an angle as shown in Figure E, and the bottom line of the sensor should be kept parallel or orthogonal to the axis of rotation of the measured object during installation. This product can be installed horizontally or vertically (vertical installation needs to be customized), and the correct installation method is shown in Figure F.

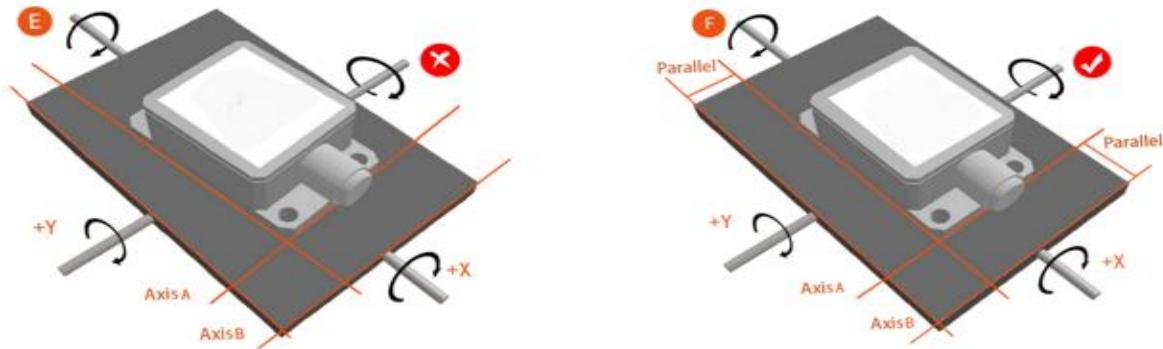


Figure 4. Installation Diagram

Finally, the mounting surface of the sensor and the surface to be measured must be tightly fixed, smooth in contact, and stable in rotation, and measurement errors due to acceleration and vibration must be avoided.

## DIMENSIONS

### Outline Dimensions

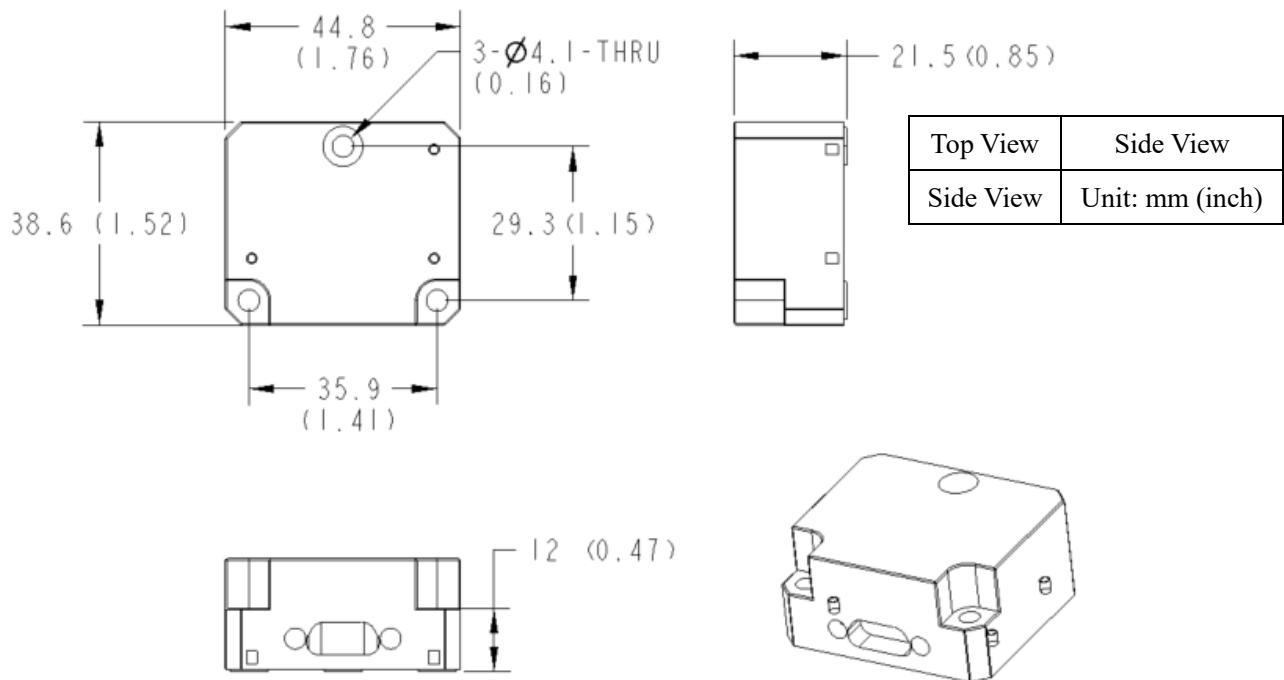


Figure 5. Outline Dimensions



Table 4. Mechanical Characteristic

Connector	J30J-15TJL (30cm)
Protection level	IP65
Shell material	Magnesium alloy sanding oxidation
Installation	Three M4 screws

## EXECUTIVE STANDARD

- National Standard for Static Calibration of Biaxial Inclination Sensors (Draft)
- GB/T 191 SJ 20873-2003 General Specification for Tiltmeters and Levelling Devices