



# TS-3420-R05 Current Output Dual Axis Inclinometer

# **Technical Manual**

#### V1.0



#### **FEATURES**

- Dual Axis Inclination Measurement
- Resolution: 0.01°
- Power Supply: 12-36V
- Size: 3.54 × 1.59 × 1.02 (inch) 90 × 40.5 × 26 (mm)
- Highest Accuracy: 0.1°
- Measurement Range: ±90°
- Output: 4-20mA/0-20mA/0-24mA optional
- IP67 Protection Level

#### **APPLICATIONS**

- Industrial Automatic Leveling
- Medical Instruments
- Photovoltaic Automatic Tracking
- Tower Tilt Monitoring
- Special Valve
- Oil Drilling Equipment
- Industrial Converter
- Lifting Equipment Inclination Control

#### DESCRIPTION

The TS-3420-R05, developed and manufactured by AIT Sensing, is a cost - effective dual - axis inclinometer. It offers current output. It incorporates a well - established industrial - grade MEMS accelerometer, with a measurement range of  $\pm 90^{\circ}$  and a maximum accuracy of 0.1°. The operating temperature range extends from  $-40^{\circ}$ C to  $+ 85^{\circ}$ C.

Compact and lightweight, the TS-3420-R05 is well suited for applications with space constraints. It converts variations in the static gravity field into changes in the inclination angle. Depending on the output type selected (analog voltage or digital), it directly provides the horizontal inclination value.

This inclinometer has numerous advantages, such as low cost, minimal temperature drift, ease of use, and strong anti - interference capabilities. Thus, it is an ideal choice for inclination measurement in industries like photovoltaic power generation, pan - tilt control, and tower monitoring.

During installation, users can employ the AIT serial port debugging assistant tool or AIT test and calibration software for on - site calibration. This helps correct any angle misalignment at the installation site.

#### **SPECIFICATIONS**

#### Table 1.

Parameter	Test Conditions	Min.	Тур.	Max.	Unit/Note
Power Supply Voltage		12		36	V
Operating Current	No load	20	50	60	mA
Output Load	Мах			500	Ω
Operating Temperature Range		-40		85	°C
Storage Temperature Range		-55		100	°C
Measurement Range			±90		0
Measurement Axis			X-Y		
Accuracy	Room temperature		0.1		o

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### **Current Output Dual Axis Inclinometer**

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Resolution	Completely still		0.01		0	
Zero bias	-40~85°C	-0.01		+0.01	°/°C	
Start-Up Time				3	S	
Output Frequency			100		Hz	
Current Octoret at 7aus	Output: 0 ~ 20V		10		v	
Current Output at Zero	Output: 0 ~ 24V		12			
Full-Scale Output Current Range		4		20	mA	
Mean Time Between Failures MTBF		90000			h	
Electromagnetic Compatibility		According to GBT17626				
Insulation Resistance		100			MΩ	
Impact Resistance		2000g, 0.5ms, 3 times/axis				
			230		g	
Weight			0.51		lbs	
			8.11		Oz	

\*Resolution: The smallest change value of the measured value that the sensor can detect and distinguish within the measurement range.

\*Accuracy: The root mean square error of the actual angle and the sensor measuring angle for multiple ( $\geq$ 16 times) measurements.



#### **ELECTRICAL INTERFACE**





Figure 2. RS 2322 Wiring Diagram

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#### **DEBUGGING SOFTWARE**

You can download the serial debugging assistant directly on the official website (technical service -> download area), or you can use the more convenient and intuitive host computer software.

TS-3420-R05 supporting serial port debugging software can connect the inclination sensor on the computer to display the angle. The software debugging interface is shown in the figure below. Using the tilt angle to debug the host computer, you can conveniently display the current X direction and Y direction tilt angle, and you can also modify and set other parameters.

Steps:

- (1). Correctly connect the serial port hardware of the inclinometer and connect the power supply.
- (2). Select the computer serial port and baud rate and click to connect to the serial port.
- (3). Click Start, the current tilt angle of the inclinometer in the X and Y directions will be displayed on the screen.

BaudRate: 9600 V Disconnected Open Refresh COM Refresh Address	Angular velocity Angle Magnetic field Gravity acceleration Angular velocity X: 0 Y: 0 Z: 0	ns	Start	time 3D Demo	
	Data Save				
	□ Save	Path:	C:\Users\Public\Docume	ents	Re_Path
	Open storage path	Name:	wis_Record	.txt	

Figure 3. Software Debugging Interface



#### **INSTALLATION**

The correct installation method can avoid measurement errors. When installing the sensor, please do the following:

First of all, make sure that the sensor mounting surface is completely close to the measured surface, and the measured surface should be as level as possible. There should be no included angles as shown in Figure A and Figure C. The correct installation method is shown in Figure B and Figure D.



Secondly, the bottom line of the sensor and the axis of the measured object cannot have an angle as shown in Figure E, and the bottom line of the sensor should be kept parallel or orthogonal to the axis of rotation of the measured object during installation. This product can be installed horizontally or vertically (vertical installation needs to be customized), and the correct installation method is shown in Figure F.



Finally, the mounting surface of the sensor and the surface to be measured must be tightly fixed, smooth in contact, and stable in rotation, and measurement errors due to acceleration and vibration must be avoided.



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#### DIMENSIONS

#### **Outline Dimensions**



Figure 4. Outline Dimensions

#### **PCB** Dimensions

The length and width may have an error of  $\pm 1$ mm, please refer to the actual product.







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Figure 6 . Top View of TS-3420-R05

Table 3. Mechanical Index

Connector	Metal joint (Cable 1.5m)
Protection level	IP67
Shell material	Magnesium aluminum alloy oxidation
Installation	Three M4 screws